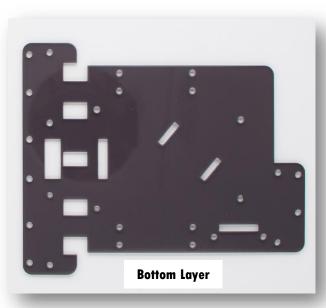
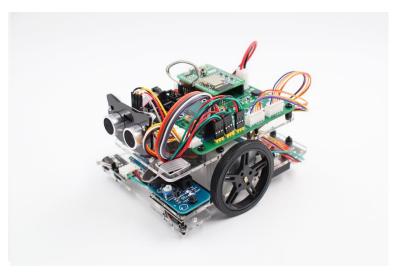
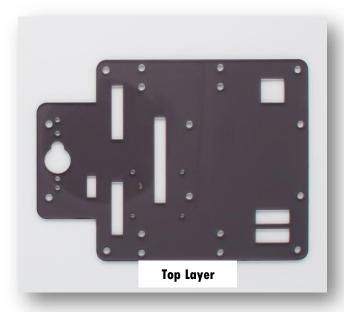
### **Preparation**

- Let's get the following items ready:
  - 1) 2 x PLA Motor Mount & Metal Screws
  - 2) 2 x Wheel Set
  - 3) 2 x Stepper Motor
  - 4) 3 x End Stop Switch & Wires
  - 5) 1 x 5-Channel Line Sensor & Wires
  - 6) 1 x Ultrasonic Sensor
  - 7) 1 x IR Sensor
  - 8) 1 x 6pin Flat Ribbon Cable (short)
  - 9) 1 x Grove to Female Dupont Jumper Cable
  - 10) Top and Bottom Acrylic Set
  - 11) 8 bags of Screw
    - i. Pack A
    - ii. Pack B
    - iii. Ultrasonic
    - iv. Base
    - v. Power
    - vi. Motor
    - vii. ToF
    - viii. Extras
  - 12) Zip ties





360 view: <a href="https://youtu.be/WTXHzbzV7Ps">https://youtu.be/WTXHzbzV7Ps</a>





# 1

### **Bottom Layer**

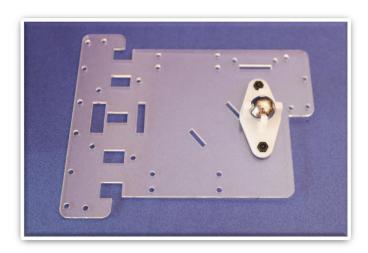
We will use Pack "A" in this step. Check if your pack has the following items:

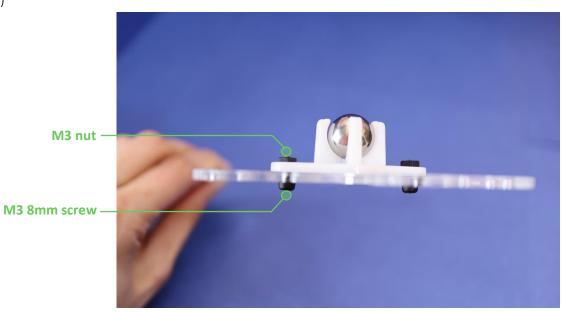
- 1 x Castor wheel
- 1 x 3D printed part (Module B)
- 1 x Blue tac (Module B)
- 2 x M3 15mm screw (Module B)
- 4 x M3 12mm screw
- 4 x M3 8mm screw
- 4 x M3 round spacer
- 8 x M3 nut
- 2 x M3 nut (Module B)

(Please safe keep all the parts in grey color, they will be used for color sensor later in Module B.)

#### a. Castor Wheel (cautious: Pay attention to the orientation of the acrylic)

- 1 x Bottom layer acrylic (remove the protective film)
- 1 x Castor wheel
- 2 x M3 8mm screw
- 2 x M3 nut

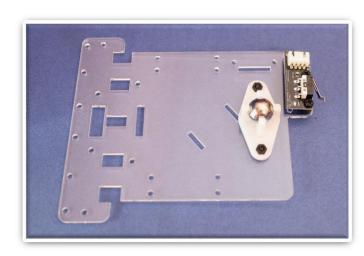


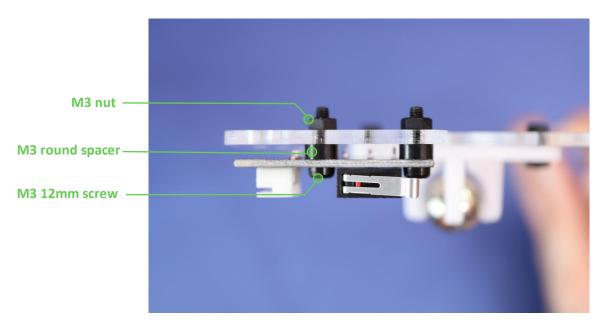


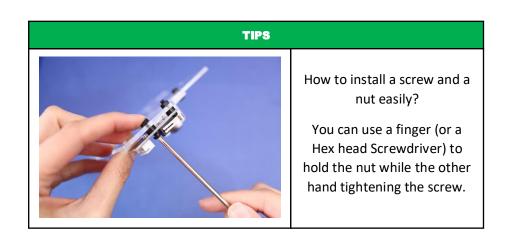


### b. End Stop Switch #1

- 1 x End stop switch
- 2 x M3 12mm screw
- 2 x M3 nut
- 2 x M3 round spacer



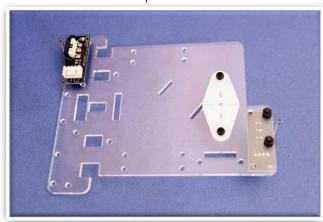


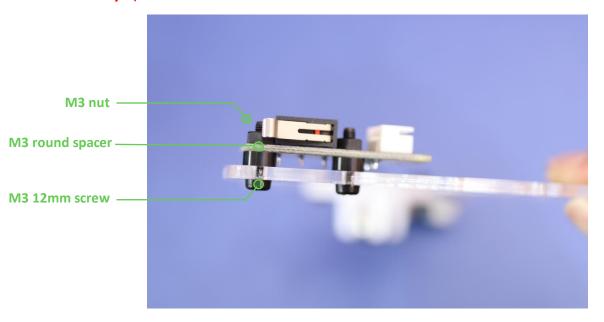




### c. End Stop Switch #2 (cautious: This step is on the reverse side of the acrylic)

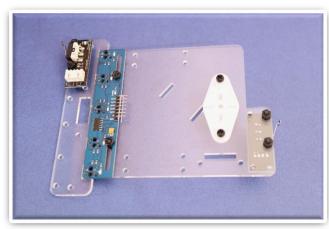
- 1 x End stop switch
- 2 x M3 12mm screw
- 2 x M3 nut
- 2 x M3 round spacer

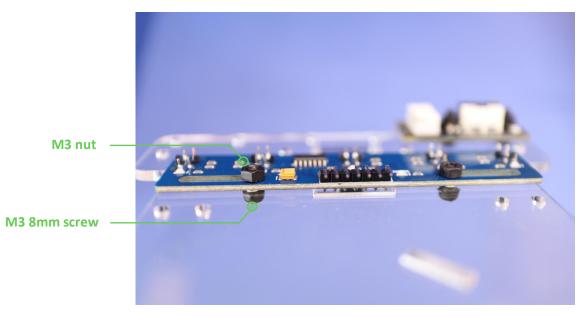




#### d. 5-Channel Line Sensor

- 1 x 5-Channel line sensor
- 2 x M3 8mm screw
- 2 x M3 nut





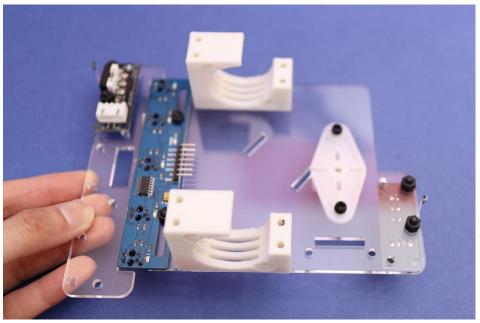


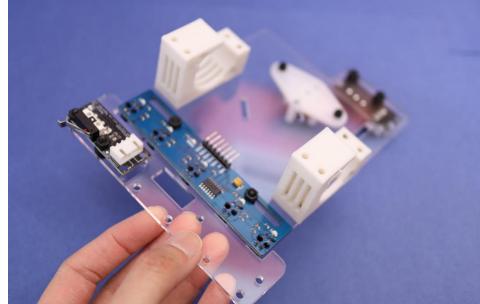


# Installing the Motor Mounts on the Acrylic

#### What you need:

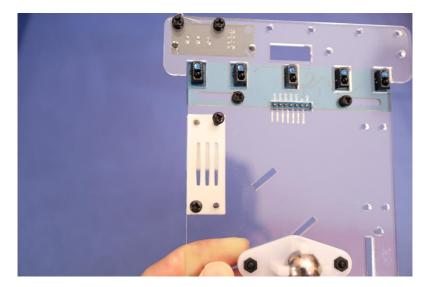
- 2 x PLA motor mount
- 8 x Stainless steel M3 45mm screw
- a. Align the motor mounts as illustrated below (cautious: Pay attention to the orientation of the mount)

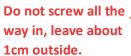


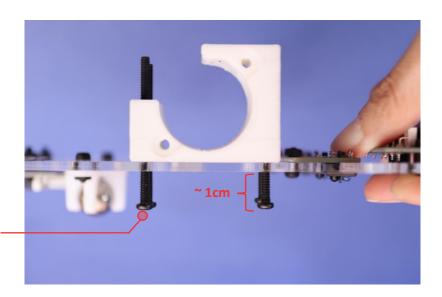


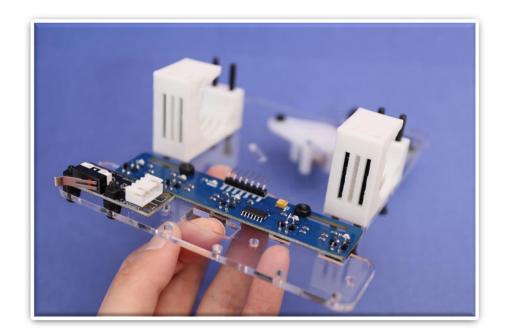


### b. Install the screws from the bottom (in a diagonal pattern)



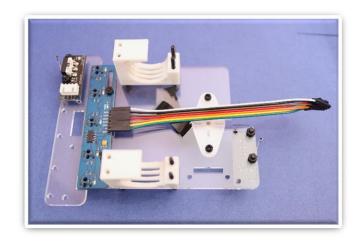


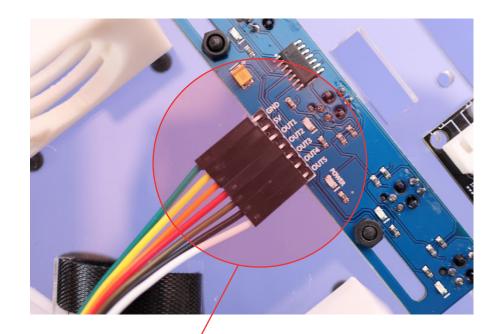






# **Connecting the Line Sensor Wire & Jotting Down the Pinouts**





Write down or take a picture of the pinouts.

#### Example:

Green : GND
Yellow : 5
Orange : OUT1
Red : OUT2
Brown : OUT3
Black : OUT4
White : OUT5

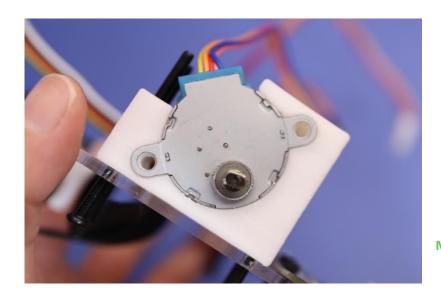


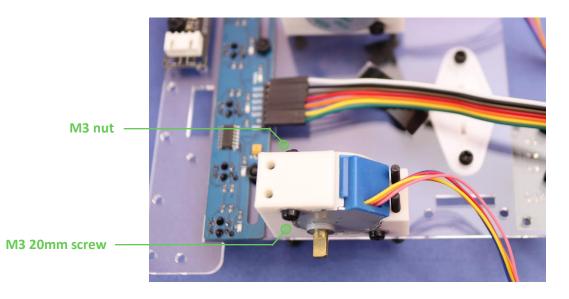


# **Installing the Motors**

#### What you need:

- Pack "Motor"
  - 4 x M3 20mm screw
  - 4 x M3 nut
  - 8 x Metal M3 nut (Place the metal nuts aside, we will use them later)





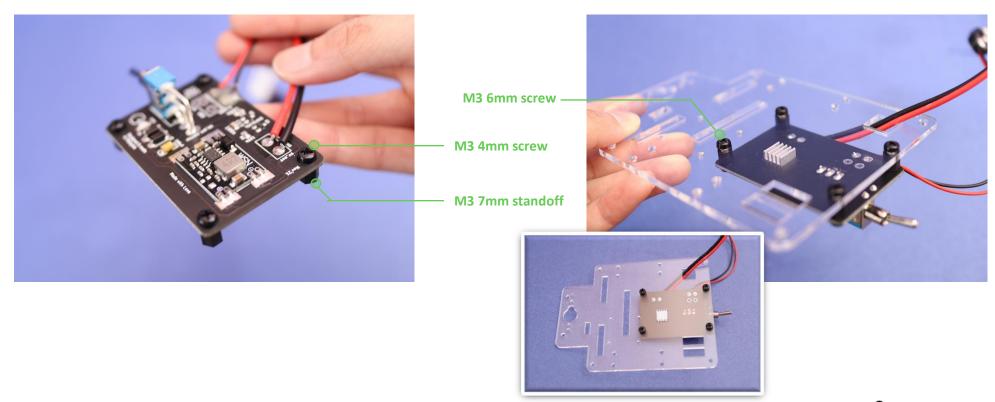


# Top Layer — Power Board

#### What you need:

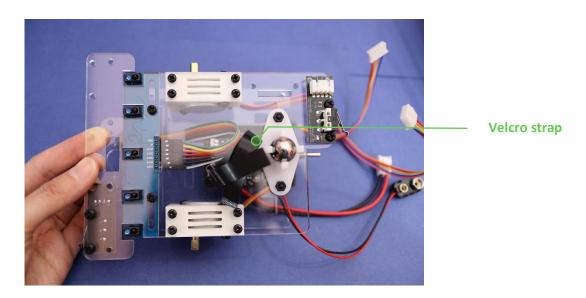
- Pack "Power"
  - 4 x M3 4mm screw
  - 4 x M3 6mm screw
  - 4 x M3 7mm standoff
  - 1 x Velcro strap
- 1 x Top layer acrylic (remove the protective film)
- 1 x Power Board

### a. Install the power board on the top layer acrylic



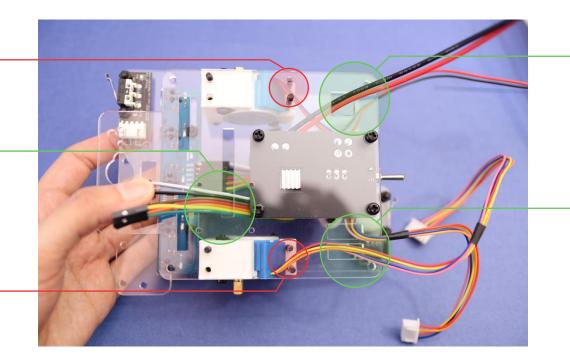
TOMATO CUBE\*

### b. Insert the Velcro strap via the holes at the bottom layer acrylic



### **Organizing the Wires**

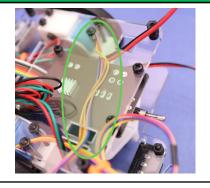
- a. Place the motor wire in between the screws
  - c. Pass the line sensor wire through the hole at Top Layer Acrylic
- b. Place the motor wire in between the screws



d. Pass the power board wire through the hole at Top Layer Acrylic

e. Pass the motor wires through the holes at Top Layer Acrylic.

#### TIPS



If you'd like the wire to be more organized, you can pass the wire from the furthest motor through the gap between the power board & acrylic (before passing it through the hole at the Top Layer Acrylic).



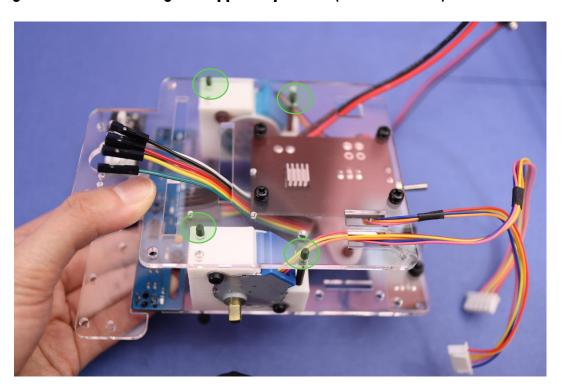


# **Installing Top Layer Acrylic on the Motor Mount**

#### What you need:

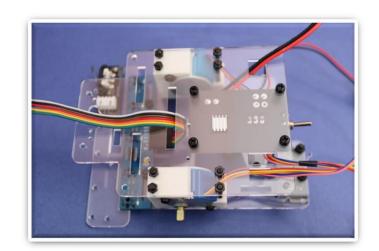
• 8 x Metal M3 nut from Pack "Motor" earlier.

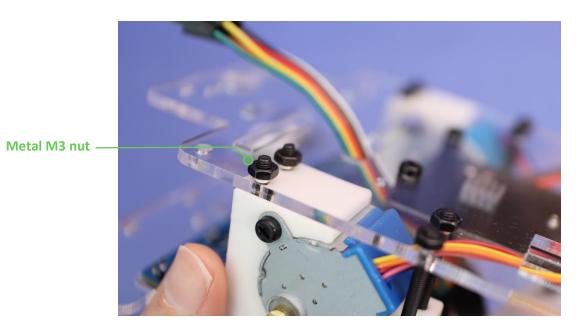
### a. Tighten 2 Screws at diagonal opposite position (for each motor)





### b. Tighten the remaining screws & insert the metal nuts





# **Installing the Ultrasonic Sensor**

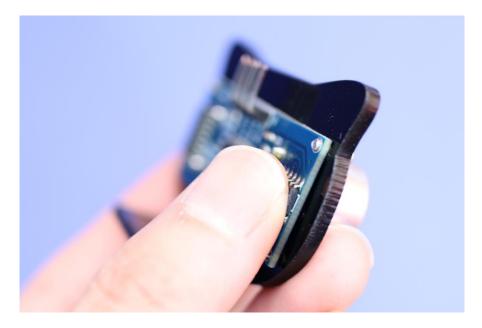
#### What you need:

- Pack "Ultrasonic"
  - 2 x Metal M2 6mm screw
  - 2 x M2 8mm screw
  - 2 x M2 nut
  - 1 x Acrylic stand (remove the protective film)

### a. Mount the ultrasonic sensor to the acrylic



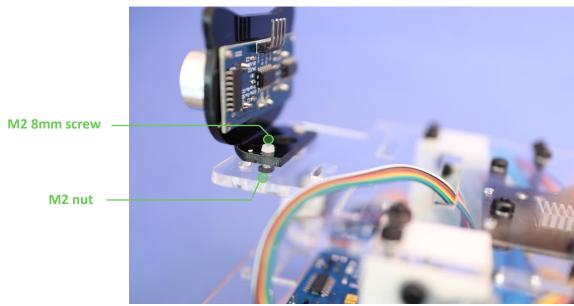
Metal M2 6mm screw

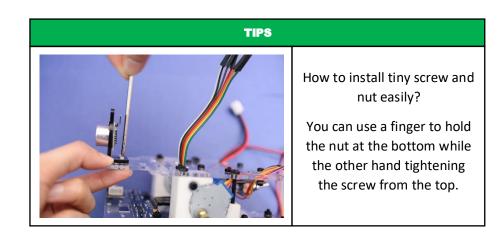




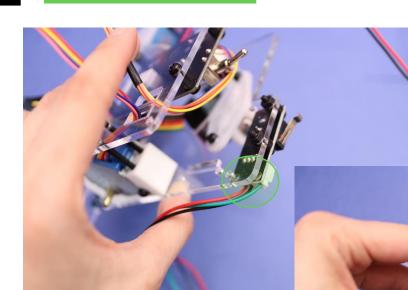
### b. Mount the ultrasonic to the top layer acrylic







# Connecting & Tidying the Wire for End-Stop Switch #1



#### WARNING



Be careful when using a scissor / cutting plier, do not cut the wire (or your finger)

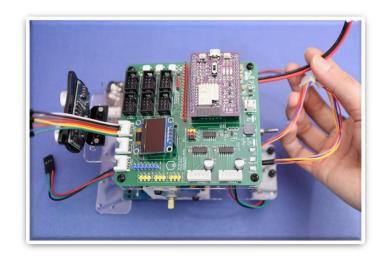
Passing the wire through the hole at Top Layer Acrylic



# **Installing the Base Board**

#### What you need:

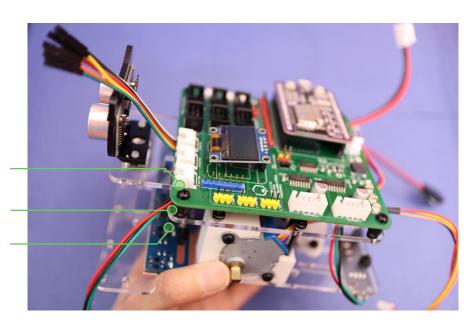
- Pack "Base"
  - 4 x M3 4mm screw
  - 4 x M3 6mm screw
  - 4 x M3 7mm standoff
- 1 x Base Board



M3 4mm screw

M3 7mm standoff

M3 6mm screw







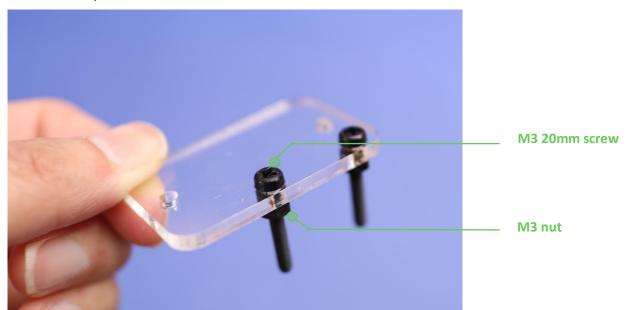
# **Installing the Double-decked sensors**

#### What you need:

- Pack "B"
  - 2 x M3 20mm screw
  - 2 x M3 12mm screw
  - 2 x M3 round spacer
  - 6 x M3 nut
  - 1 x small acrylic (remove the protective film)
- 1 x End-stop switch
- 1 x IR sensor

### a. Install the screws & nuts on the small acrylic

- 2 x M3 20mm screw
- 2 x M3 nut
- 1 x acrylic

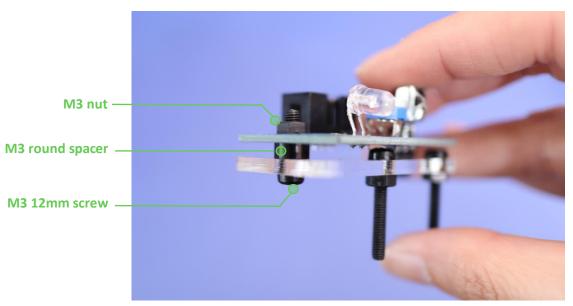




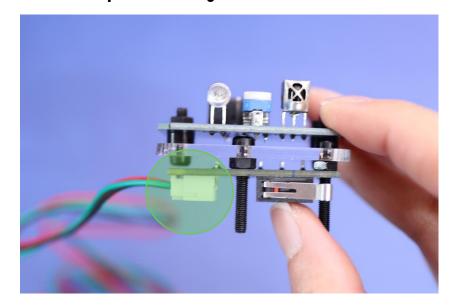
### b. Install the IR sensor

- 2 x M3 12mm screw
- 2 x M3 round spacer
- 2 x M3 nut
- 1 x IR sensor



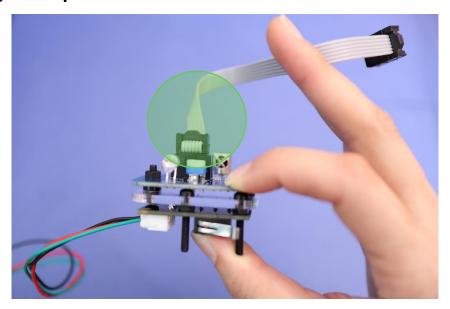


### c. Insert the end-stop switch & Plug in the wire



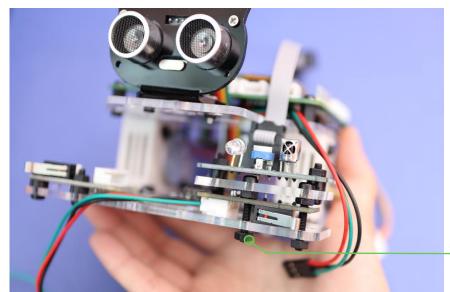


### d. Plug in the 6pin flat ribbon cable



### e. Install the double-decked sensor at the Bottom Layer Acrylic

• 2 x M3 nut

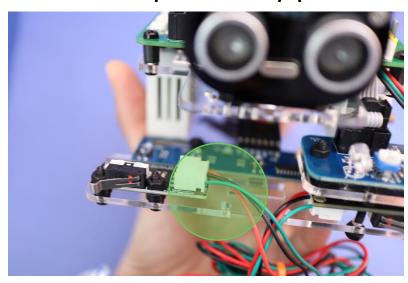


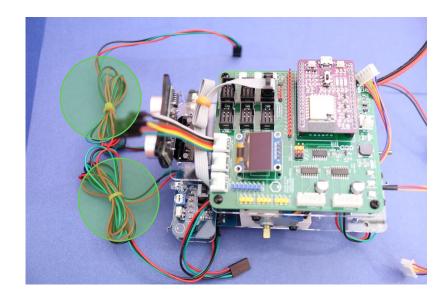
M3 nut



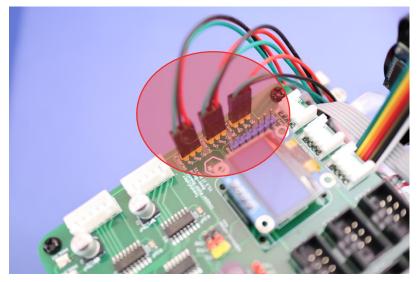
# **Connecting & Tidying the Wires**

a. Plug in the wire for end-stop switch #2 & tidy up all the wires





b. Plug in the end-stop switch wires to the main board. (cautious: Pay attention to the pinouts & the color of the wires.)



**Green Wire: SIG** 

**Black Wire: GND** 

**Red Wire: VCC** 



c. Plug in the line sensor wires to the main board (cautious: Pay attention on the pinouts & the color of the wires. Refer to your note on step #3.)

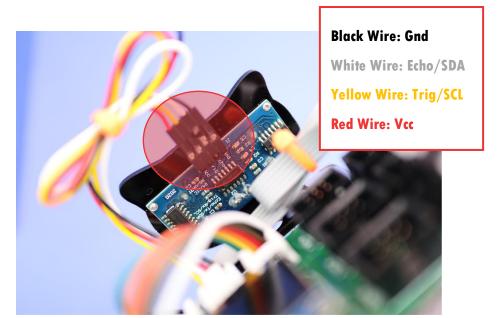


d. Plug in the IR sensor flat cable to the main board & tidy up the cable.

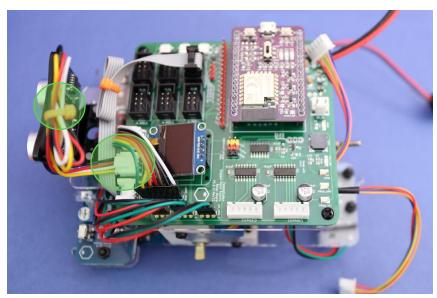
(You can plug it into any of these six 6-pin shrouded connectors on the main board.)



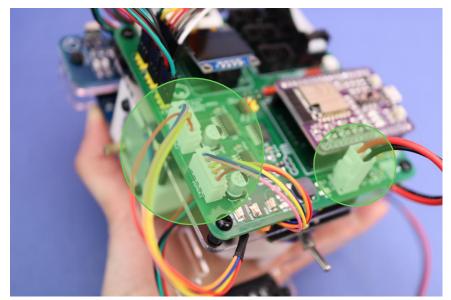
e. Plug in the ultrasonic wires to the main board & tidy up the wires (cautious: Pay attention on the pinouts & the color of the wires)



You can plug it into any of these 3 grove connectors on the main board.



f. Plug in the motor wires & power board cable to the main board. (Jot down which side of your motor goes to stepper\_1 & stepper\_2)

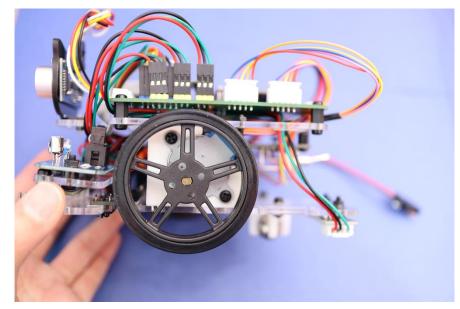


# Installing the wheels

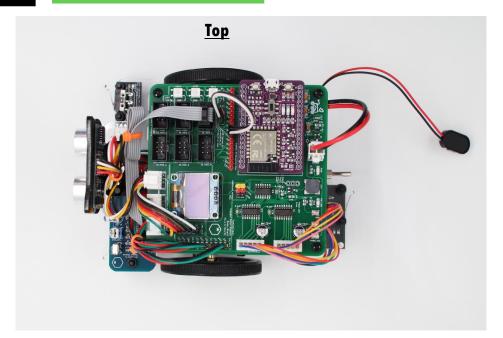
### What you need:

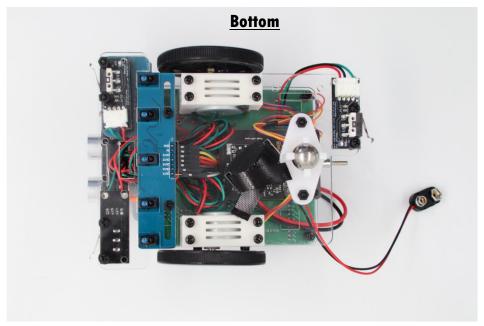
• 2 x Wheel set

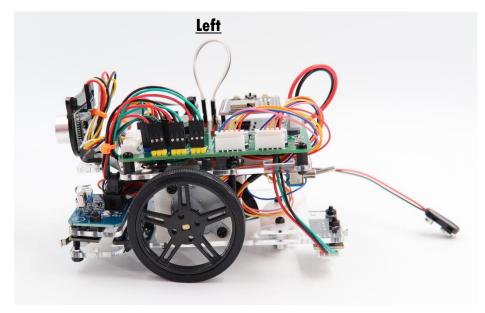


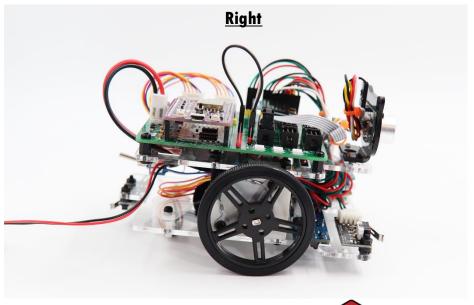


# **Final Check**



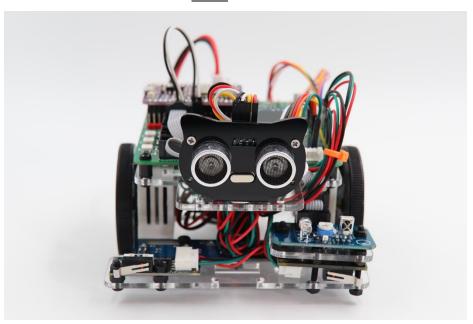


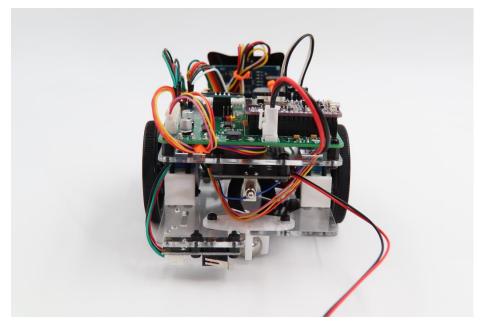






<u>Front</u> <u>Back</u>





#### WARNING



Do not plug in the battery until you are told to do so. Failure to follow this instruction might cause damage to the modules & sensors.